i.MX53 Development Kit QUICK GUIDE



Release Date: January 15, 2013

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About Voipac i.MX53 Development kit

Voipac i.MX25 SODIMM Baseboard is designed to be used as development platform for the Voipac cross-compatible i.MX53/i.MX51/i.MX25 SODIMM Modules. Together they create a low power system with excellent MIPS/mW performance allowing deployment in situation where power source is limited. Besides the standard PC peripheral interfaces, the system provides numerous communication channels as well as universal expansion slots and connectors.

This QuickGuide shows, how to install JTAG Cable, load Linux using TeraTerm. Programs run under Windows XP.

COMPONENTS	QUANTITY
SODIMM Base Board	1
SODIMM Module	1
JTAG cable with serial line	1
Support CD	1
Aluminium case set	1
Serial port cable	1
Crossover Ethernet cable	1
SODIMM socket	1
JTAG pitch compression connector	1
SODIMM Module Printed Schematics	1
Mounting Fastener	2
Quickguide Brochure	1
DATAIMAGE TFT display with touchscreen set (Optional)	1
OPTREX TFT display with touchscreen set (Optional)	1
EDT TFT multitouch capacitive display with mounting ears set (Optional)	1







Connecting the components and cables

Prepare Baseboard and plug in JTAG Cable with Serial line, Ethernet cable and other devices or interfaces you need.



First Step

The development kit is supplied with pre-installed bootloader, linux kernel and demo file system. The development kit can be controlled over:

Controlling the Development Kit over serial line

Recommended HW:

- a) PC with serial port or USB to serial adapter
- b) Voipac i.MX53 development kit
- c) Voipac serial cable (<u>http://voipac.com/#X25-SPC-000</u>)

Recommended SW:

Serial line terminal (PUTTY, Minicom, Ckermit, Hyperterminal, TeraTerm, ...)

Default serial port settings:

Speed (baud):	115200
Data bits:	8
Stop bits:	1
Parity:	None
Flow control:	None

Controlling the development kit using TeraTerm

👺 COM1:115200baud - Tera Term VT				×
<u> E</u> ile <u>E</u> dit <u>S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp				
Mounting /dev/shm]	OK	1	~
Mounting /mnt/rwfs	I	OK	1	-
Mounting root as RW	Ε	OK	1	
Mounting fstab devices	Ι	OK	1	
Running sysctl	Ι	OK	1	
Setting up networking on loopback device	I	OK	1	
Starting DHCP for interface eth0				
eth0: Freescale FEC PHY driver [Generic PHY] (mii_bus:phy_addr=0:lf,	irq=	-1)		
PHY: 0:1f - Link is Up - 100/Full	I	OK	1	
Starting inetd [telnet] [ssh] [ftp]	I	OK	1	
Starting klogd	Ι	OK	1	(B)
Starting syslogd	I	OK	1	
ntpd: bad address 'l.europe.pool.ntp.org'				
Setting time from ntp server: l.europe.pool.ntp.org]	OK	1	
Local script : start	E	OK	1	
; Hardware: Voipac Technologies				
Processor: ARMv7				
: `; :' .; :: :: .; `' .; ; '' RAM: 902MB FREE: 875MB				
`'`': ;:'`. , ;`' ROM: 227.2MB FREE: 214.4MB				
ROOT: whifs				
:_; IP: 192.168.0.11				
vmx53 login:				~

Using external monitor (or supplied TFT panel) and USB Keyboard

Recommended HW:

- a) External monitor with DVI or VGA connector (for VGA monitor is required to use DVI to VGA adapter) DATAIMAGE TFT Display (optional, <u>http://voipac.com/#27M-TFT-000</u>) OPTREX TFT Display (optional, <u>http://www.voipac.com/#X51-TFT-000</u>) EDT TFT Display (optional, <u>http://voipac.com/#X53-TFT-000</u>)
- b) Voipac i.MX53 development kit

Recommended SW:



IMPORTANT!

External monitor must support at least one of following resolutions 640x480px, 800x480px, 800x600px, 1024x720px, 1280x800px or 1600x1200px.

Controlling the development kit using external monitor and USB Keyboard



Illustration Photo

Controlling the Development Kit over Ethernet (telnet, ssh, ftp, sftp)

Recommended HW:

- a) PC with Ethernet
- b) Voipac i.MX53 development kit
- c) Ethernet cable (<u>http://voipac.com/#X25-CEC-000</u>)

Recommended SW:

- Telnet client (Telnet, PUTTY, ...)
- SSH client (SSH,PUTTY, ...)
- FTP client (FTP, Filezilla, BareFTP, ...)
- SFTP client (Filezilla, PUTTY, WinSCP, ...)

IMPORTANT!

Demo modules are shipped with empty root password. The default IP address is dynamic and setup by your dhcp server upon boot.

SSH, SFTP require root password to be set up. ("passwd" command) FTP, SFTP are recommended only for data transfers. (binary mode is recommended)

Controlling the development kit using PUTTY



Controlling the development kit using WinSCP (Explorer Interface)

🚡 utils - 192.168.0.11 - Wi	nSCP					$ \times $
Eile ⊆ommands <u>M</u> ark <u>S</u> ession (⊻iew <u>H</u> elp					
Address 🗀 /utils					~	\bigcirc
🔃 🖬 🖬 👘	📝 🛳 🗙 🖆	r 🖉 🖄	i 💷 🧬 🗎	🕈 📀 🐕		
🌻 🖾 🕈 🔢 🗊 🕇 🏪 De	fault	💌 🕴 😻 -	•			
☐ / <root></root>						^
	canconfig	candump	canecho	cansend	cansequence	
					2 58	
	ethtool	evtest	fm	fmscan	gdb_sample	
	C	<u>eta</u>	<u>eta</u>	<u>984</u>	<u>984</u>	
	gdb_sample.c	gdbserver	i2cdetect	i2cdump	i2cget	
						~
0 B of 3 729 KiB in 0 of 37			â	FTP	0:00:5	8 🔡

Open On-Chip Debugger 0.6.0 with Voipac's JTAG Cable under WinXP

JTAG Cable Installation

1 Connect JTAG Cable to USB port on your computer. JTAG Cable will be installed automatically and prepared for usage.

2 Download OpenOCD v 0.6.0 (http://www.voipac.com/downloads/imx/jtag/bin/openocd-0.6.0-vmx0.zip).

3 Unzip the file and place to the folder you want to.

How to run Open On-Chip Debugger

4 Run OpenOCD using, for example, Total Commander. Open the folder where is placed the unzipped file. Type in command line: **openocd -f vmx53w.cfg**. Press [Enter].

💾 Total Comman	der 7.56	a - NOT F	REGISTERED							×
<u>Files Mark Comma</u>	nds <u>N</u> et	Sho <u>w</u> C <u>o</u>	nfiguration <u>S</u> ta	rt					ţ	Help
	3 69	1					\$ 5			
📼 c 🚩 [_none_]	9 064 64	0 k of 33 l	013 540 k free	- X	🖃 c 🚩 [_none_]	9 064 64	0 k of 33 l	013 540 k free	\	
▼c:\Program Files\	openocd	-0.6.0-vm	(O*.*	* 🔻	★c:\Program Files	\WinSCP\	*.*		*	-
↑Name	Ext	Size	Date	Attr	Name	Ext	Size	+ Date	Attr	
\$ []		<dir></dir>	12.09.2012 1	3:54 🔥	仓[]		<dir></dir>	17.04.2012 14	:35	~
🗀 (vmx25)		<dir></dir>	12.09.2012 1	3:54	[][PuTTY]		<dir></dir>	17.04.2012 14	:34	
🚞 (vmx51)		<dir></dir>	12.09.2012 1	3:54	🗋 unins000	dat	72 048	17.04.2012 14	:34-a	۵
🦲 (vmx53)		<dir></dir>	12.09.2012 1	3:54 📃	🕘 unins000	msg	12 781	17.04.2012 14	:34-a	
openocd	exe	1 708 866	12.09.2012 1	3:03-a	15 unins000	exe	710 808	17.04.2012 14	:33-a	
🔡 vmx53 w	cfg	5 477	12.09.2012 1	3:21-a 💌	🖄 DragExt	dll	78 544	18.02.2012 21	:35-a	~
0 k / 1 683 k in 0 / 4 file(s), 0 / 3 dir(s) 0 k / 8 559 k in 0 / 10 file(s), 0 / 1 dir(s)										
c:\Program File	es\openo	cd-0.6.0-v	mx0 openoc	d.exe -f vmx5	3w.cfg					*
F3 View	F4 E	dit	F5 Сору	F6 M	ove F7 Newl	older	F8 Del	ete Alt-	F4 Exit	

Open On-Chip Debugger is running.



How to connect to Open On-Chip Debugger using Telnet

5 Click on Start/Run, type telnet localhost 4444 and click on OK button.



Open On-Chip Debugger is running.



How to connect to Open On-Chip Debugger using terminal (TeraTerm)

6 Open TeraTerm program, click on File/New Connection, check TCP/IP and type **4444** into TCP port# field. Press OK.

⊙ <u>т</u> ср/ір тср	Host: 127.0.0.1
O <u>S</u> erial	

Open On-Chip Debugger over TeraTerm program is running.



7 step

Open TeraTerm program, click on File/New Connection, check Serial and choose the port where the JTAG cable is connected to a PC.

Tera Term: N	ew connection
О <u>т</u> сруір	Host: 127.0.0.1 TCP port#: 23 Protocol: UNSPEC → ✓ Telnet
⊙ <u>S</u> erial	Po <u>r</u> t: COM4: USB Serial Port (COM4)
	OK Cancel <u>H</u> elp

🖳 сом 4	:38400baud - Te	era Term VT 📃 🗖	X
Eile Edit	Setup Control W	Tera Term: Serial port setup	_
	Window Font Keyboard	Port: COM4 V OK	
	Serial port TCP/IP General	Data: 8 bit Cancel	
	Additional setting Save setup Restore setup	P <u>a</u> rity: none ♥ <u>S</u> top: <u>1 bit ♥</u> <u>H</u> elp	
	Load key map	Elow control:	
		Transmit delay O msec <u>/c</u> har O msec <u>/l</u> ine	>

How to load bootloader into i.MX53 SODIMM Module (barebox.bin)

Check **H902** jumper (BOOTMODE) on the baseboard to select **Serial boot**, by connecting pins 1 and 2 together.

Direct Boot (Boot from E-Fuses) is selected as the bootmode by connecting pins 2 and 3 together.



Serial Boot

Direct Boot (Boot from E-Fuses)



9 Step

> (Note) Serial Boot is for the first flashing of the module or if the image written in the Flash cannot boot. Direct Boot is for normal module working

Type reset_halt and press [Enter].

🖳 127.0.0.1:4444 - Tera Term VT	×
<u>Eile E</u> dit <u>S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp	
Open On-Chip Debugger reset_halt adapter speed: 100 kHz number of cache level 2 cache 12 present :not supported mpdir not in multiprocessor format target state: halted target halted in ARM state due to debug-request, current mode: Supervisor cpsr: 0x000001d3 pc: 0x7ff09860 MMU: disabled, D-Cache: disabled, I-Cache: enabled breakpoint set at 0x00000000 target state: halted target halted in ARM state due to breakpoint, current mode: Supervisor cpsr: 0x000001d3 pc: 0x00000000 MMU: disabled, D-Cache: disabled, I-Cache: disabled >	
	~

Type **step** and press [Enter].

<u>File Edit S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp
> reset_halt
adapter speed: 100 kHz
number of cache level 2
cache 12 present :not supported
mpdir not in multiprocessor format
target state: halted
target halted in ARM state due to debug-request, current mode: Supervisor
cpsr: 0x000001d3 pc: 0x7ff09860
MMU: disabled, D-Cache: disabled, I-Cache: enabled
breakpoint set at UXUUUUUUUU
target state: halted
target halted in ARM state due to breakpoint, current mode: Supervisor cpsr: 0x000001d3 pc: 0x00000000
MMU: disabled, D-Cache: disabled, I-Cache: disabled
) step
target state: halted
target halted in ARM state due to breakpoint, current mode: Supervisor
cpsr: 0x000001d3 pc: 0x0040e568
MMU: disabled, D-Cache: disabled, I-Cache: disabled

Type resume and press [Enter].



Type vmx53_init and press [Enter].

😕 127.0.0.1:4444 - Tera Term VT	. 🗆 🔀
<u>Eile E</u> dit <u>S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp	
MMU: disabled, D-Cache: disabled, I-Cache: disabled	~
> step target state: balted	
target halted in ARM state due to breakpoint, current mode: Supervisor cpsr: 0x000001d3 pc: 0x0040e568	
MMU: disabled, D-Cache: disabled, I-Cache: disabled	
> resume > vmx53_init Configuring VMX53	
target state: halted	
target halted in ARM state due to debug-request, current mode: Supervisor	
Cpsr: UX800001d3 pc: UX/II06/C4 MMU: disabled D_Carba: disabled T_Carba: anabled	
core state: ARM	
cpsr (/32): 0x000001D3	
adapter speed: 1000 kHz	
ap 1 selected, identification register 0x24770002	
ap 0 selected, identification register 0x44770001	
Initialisation completed	~

Type boot and press [Enter].



Barebox is loaded into the i.MX53 module SRAM.

(Note) After "boot" the barebox is being executed.

The previously loaded bootloader (barebox.bin) is running in Serial console.





When the module is switched off, barebox is erased. To flash barebox again, it is needed to use the same procedure as shown in Step 10.

OpenOCD must be closed and restarted again to use the same procedure as shown in Step 10.

11 Run TFTP server. Type or paste commands in Serial console to set Ethernet:

Assign individual IP addresses according to the specifications of your subnet.

```
eth0.ipaddr=192.168.0.150
eth0.netmask=255.255.255.0
eth0.gateway=192.168.0.1
eth0.serverip=192.168.0.77
```

🛎 COM1:115200baud - Tera Term VT 📃 🗖 🔀						
File Edit Setup Control Window Help						
imx-esdhc@mcil: registered as mcil						
m25p@m25p0: sst25 m25p@m25p1: sst25	Tera Term: Clipboard confirmation 🛛 🔀					
NAND device: Manu) Bad block table n Bad block table n Scanning device f Bad block table w Bad block table w detected i.MX53 r Malloc space: 0x7 Stack space : 0x7	eth0.ipaddr=192.168.0.154 eth0.netmask=255.255.255.0 eth0.gateway=192.168.0.1 eth0.serverip=192.168.0.77 Сапсе Сапсе	L				
envfs: wrong magi no valid environm running /env/bin/	it it					
Hit any key to sto barebox:/ barebox:/ []	p aucopoot. J					

Type or paste commands in Serial console to erase Flash:

erase /dev/nand0

🐸 COM1:115200baud - Tera Term VT	
<u> Eile E</u> dit <u>S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp	
Bad block table written to 0x0ffc0000, version 0x01 detected i.MX53 rev 2.1 Malloc space: 0x7f700000 -> 0x7fefffff (size 8 MB) Stack space : 0x7f6f8000 -> 0x7f700000 (size 32 kB) envfs: wrong magic on /dev/env0 no valid environment found on /dev/env0. Using default environment running /env/bin/init	
Hit any key to stop autoboot: 3 barebox:/ barebox:/ eth0.ipaddr=192.168.0.154 barebox:/ eth0.netmask=255.255.0 barebox:/ eth0.gateway=192.168.0.1 barebox:/ eth0.serverip=192.168.0.77 barebox:/ erase /dev/nand0 barebox:/	

Type or paste command separately in Serial console to load bootloader file barebox.bin:

tftp tftp folder/barebox.bin /dev/nand0.barebox.bb

SCOM1:115200baud - Tera Term VT	
<u>File E</u> dit <u>S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp	
envfs: wrong magic on /dev/env0 no valid environment found on /dev/env0. Using default environment running /env/bin/init	^
Hit any key to stop autoboot: 1 invalid magic 0xffffffff barebox:/ eth0.ipaddr=192.168.0.154 barebox:/ eth0.netmask=255.255.255.0 barebox:/ eth0.gateway=192.168.0.1 barebox:/ eth0.serverip=192.168.0.77 barebox:/ erase /dev/nand0	
Skipping bad block at 0x0ff80000 Skipping bad block at 0x0ffa0000 Skipping bad block at 0x0ffc0000 Skipping bad block at 0x0ffe0000 barebox:/ tftp vmx53/barebox.bin /dev/nand0.barebox.bb	
phy0: Link 13 up - 1000/Full TFTP from server 192.168.0.77 ('vmx53/barebox.bin' -> '/dev/nand0.barebox ####################################	:.bb')

Final step is to power off the board and disconnect the jtag cable. Change **H902** jumper (BOOTMODE) on the baseboard by connecting pins 2 and 3 together. Power on the board. The module will boot barebox.

🖳 🖂 🖾 COM1:115200baud - Tera Term VT	×
<u>File E</u> dit <u>S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp	
<pre>registered netconsole as csl eth@eth0: got preset MAC address: 00:0D:15:00:9B:7E imx-esdhc@mci0: registered as mci0 imx-esdhc@mci1: registered as mci1 m25p@m25p0: sst25vf032b (4096 Kbytes) m25p@m25p1: sst25vf032b (4096 Kbytes) NAND device: Manufacturer ID: 0x2c, Chip ID: 0xda (Micron NAND 256MiB 3,3V 8-bit) Bad block table found at page 131008, version 0x01 Bad block table found at page 130944, version 0x01 detected i.MX53 rev 2.1 Malloc space: 0x7f700000 -> 0x7fefffff (size 8 MB) Stack space : 0x7f6f8000 -> 0x7f700000 (size 32 kB) envfs: wrong magic on /dev/env0 no valid environment found on /dev/env0. Using default environment running /env/bin/init</pre>	
Hit any key to stop autoboot: l invalid magic Oxffffffff barebox:/	•

How to flash zimage and rootfs through the TeraTerm

12 step

Type or paste commands into TCP/IP console (Open On-Chip Debugger connection):

Type: eth0.serverip=192.168.0.77 (IP address of FTP in case, no DHCP Next-Server in your subnet) Type: update barebox tftp folder/barebox-2012.09.0-vmx53-vpac0.bin

🖳 COM1:115200baud - Tera Term VT	
<u> Eile E</u> dit <u>S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp	
barebox:/	~
barebox:/eth0.serverip=192.168.0.77	_
barebox:/update barebox vmx53/barebox-2012.09.0-vmx53-vpac0.bin	
phy0: Link is up - 1000/Full	
DHCP client bound to address 192.168.0.11	
host 192.168.0.77 is alive	
erasing partition /dev/nand0.barebox.bb	
flashing vmx53/barebox-2012.09.0-vmx53-vpac0.bin to /dev/nand0.barebox.bb	
TFTP from server 192.168.0.77 ('vmx53/barebox.bin' -> '/dev/nand0.barebox.bb') ###################################	

Type erase /dev/nand0.bareboxenv and reset the board.



Type update kernel tftp folder/zlmage-2.6.35.3-vmx53-vpac0.bin.

📴 COM1:115200baud - Tera Term VT	
<u>Eile E</u> dit <u>S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp	
barebox:/ erase /dev/nand0.bareboxenv	~
barebox:/ update kernel vmx53/zImage-2.6.35.3-vmx53-vpac0.bin	
error frame: UX/F/U615U UXUUUUU882	
DHCP client bound to address 192.168.0.11	
host 192.168.0.77 is alive	
erasing partition /dev/nand0.kernel.bb	
flashing vmx53/zImage-2.6.35.3-vmx53-vpac0.bin to /dev/nand0.kernel.bb	
TFTP from server 192.168.0.77 ('vmx53/zImage' -> '/dev/nand0.kernel.bb')	
************	£.
2	
· · · · · · · · · · · · · · · · · · ·	

	-
Datebox:/ -	

Type update rootfs tftp folder/rootfs-ubifs-bb-1-18-vmx53-vpac0.bin.

🚨 COM1:115200baud - Tera Term VT <u>File Edit Setup Control Window Help</u> barebox:/update rootfs vmx53/rootfs-ubifs-bb-1-18-vmx53-vpac0.bin error frame: UX/1/Ublue UXUUUUU882 DHCP client bound to address 192.168.0.11 host 192.168.0.1 is alive erasing partition /dev/nand0.rootfs attaching UBI to /dev/nand0.rootfs UBI: attaching mtd0 to ubi0 UBI: physical eraseblock size: 131072 bytes (128 KiB) UBI: logical eraseblock size: 129024 bytes UBI: smallest flash I/O unit: 2048 UBI: sub-page size: 512 UBI: VID header offset: 512 (aligned 512) UBI: data offset: 2048 UBI: empty MTD device detected UBI: create volume table (copy #1) UBI: create volume table (copy #2) registering /dev/ubi0 UBI: attached mtd0 to ubi0 UBI: MTD device name: "nand0.rootfs" 507 MiB UBI: MTD device size: UBI: number of good PEBs: 4052 UBI: number of bad PEBs: 4 128 UBI: max. allowed volumes: UBI: wear-leveling threshold: 4096 UBI: number of internal volumes: 1 UBI: number of user volumes: 0 UBI: available PEBs: 4008 UBI: total number of reserved PEBs: 44 UBI: number of PEBs reserved for bad PEB handling: 40 UBI: max/mean erase counter: 1/0 registering rootfs as /dev/ubi0.rootfs flashing vmx53/rootfs-ubifs-bb-1-18-vmx53-vpac0.bin to /dev/ubi0.rootfs TFTP from server 192.168.0.77('vmx53/rootfs-ubifs-bb-1-18-vmx53-vpac0.bin' -> '/ dev/ubi0.rootfs') barebox:/ 📕

Type **reset** or reset the board and module will boot Filesystem. Type vmx53 login "**root**" and press [Enter].

👺 COM1:115200baud - Tera Term VT		
Eile Edit Setup Control Window Help		
ے: ۱۰۰۰ (۱۰۰۰ (۱۰۰۰ (۱۰۰۰ (۱۰۰۰)) ۱۰۰۰ (۱۰۰۰ (۱۰۰۰ (۱۰۰۰ (۱۰۰۰)) ۱۰۰۰ (۱۰۰۰ (۱۰۰۰ (۱۰۰۰))	Hardware: Voipac Technologies Processor: ARMv7 RAM: 902MB FREE: 875MB ROM: 227.2MB FREE: 214.4MB ROOT: ubifs IP: 192.168.0.11	
vmx53 login:		~

Important and Practical Information

E-Fuses

Voipac i.MX53 SODIMM Module is delivered with e-fuses set to boot from NAND interface defaultly. Upon a customer request, Voipac offers not programmed modules or modules with different boot device. The options are: NAND Flash, microSD/MMC, SPI Flash, I2C EEPROM.

To be able to put pullups on boot configuration pins you have to lock e-fuses configuration by programming the e-fuses using barebox bootloader.

Before programming e-fuses, it is needed to enable e-fuse supply gate:

```
barebox:/ md 0x53fd4064+4
53fd4064: 0000fe62
barebox:/ mw 0x53fd4064+4 0xfe72
```

b...

To dump factory e-fuses configuration use barebox command

To write e-fuses use barebox command (example writes MAC address 00:01:02:03:04:05)

barebox:/ imx_iim0.permanent_write_enable=1 barebox:/ mw -b -d /dev/imx_iim_bank1 9+6 0x00 0x01 0x02 0x03 0x04 0x05 barebox:/ md -b -s /dev/imx_iim_bank1 00000000: 01 00 00 00 00 00 00 00 00 00 01 02 03 04 05 00++..... 00000010: 00 00 00 00 00 00 19 00 00 00 00 00 00 00 00 00



BE AWARE THAT E-FUSES PROGRAMING IS NON REVERSAL PROCESS !!! WARRANTY CLAIM CAUSED BY IMPROPER E-FUSES PROGRAMMING WILL NOT BE ACCEPTED !!!

Changing MAC Address

MAC address (indicated on the label of the module) is defaultly written in e-fuses for permanent identifying the module. Customer can change the MAC address using barebox:

Stop autoboot and write: edit env/config

🖳 COM1:115200baud - Tera Term VT	
<u> Eile E</u> dit <u>S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp	
barebox://edit_env/config	^
env/config <ctrl-d>: Save and quit <ctrl-c>: quit #!/bin/sh</ctrl-c></ctrl-d>	
# can be either 'net' or 'jffs2' or 'ubifs' kernel=nand root=ubifs	
basedir=vmx53 barebox=\$basedir/barebox.bin zimage=\$basedir/zImage rootfs=\$basedir/rootfs.bin	
autoboot_timeout=3	
<pre># vmx53 modes # vmx53 modes # video=mxcdi0fb:RGB24,[VGA SVGA XGA WXGA UXGA OPTREX DATAIMAGE],bpp=[16 24 bootargs="console=ttymxc0,115200 otg_mode=host video=mxcdi0fb:RGB24,XGA,bpp</pre>	1 32] =16"

Scroll down to a last line for changing the MAC address: 00:01:02:03:04:05

😕 COM1:115200baud - Tera Term VT 📃 🗖	$\mathbf{ imes}$
<u> Eile Edit S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp	
env/config <ctrl-d>: Save and quit <ctrl-c>: quit zimage=\$basedir/zImage rootfs=\$basedir/rootfs.bin</ctrl-c></ctrl-d>	~
autoboot_timeout=3 # vmx53 modes # video=mxcdi0fb:RGB24,[VGA SVGA XGA WXGA UXGA 0PTREX DATAIMAGE],bpp=[16 24 32] bootargs="console=ttymxc0,115200 otg_mode=host video=mxcdi0fb:RGB24,XGA,bpp=16"	
nand_parts="384k(barebox)ro,640k(bareboxenv),4M(kernel),-(rootfs)" spi_parts="384k(barebox)ro,128k(bareboxenv),-(kernel)" rootpartnum_nand=3 ubiroot="rootfs"	
# ip=off static dhcp # use 'dhcp' to do dhcp in barebox and in kernel ip=dhcp	
#eth0.ethaddr=00:01:02:03:04:05	~

Rewrite the MAC address and and press [CTRL+D]

🐸 COM1:115200baud - Tera Term VT				
<u>File E</u> dit <u>S</u> etup C <u>o</u> ntrol <u>W</u> indow <u>H</u> elp				
env/config <ctrl-d>: Save and quit <ctrl-c>: quit</ctrl-c></ctrl-d>	^			
# ip=off static dhcp				
# use 'dhcp' to do dhcp in barebox and in kernel				
Th-mich				
#eth0.ethaddr=00:0d:15:00:00	~			

Type **saveenv** and press [Enter]

😕 COM1:115200baud - Tera Term VT						
<u>F</u> ile	<u>E</u> dit	<u>S</u> etup	Control	<u>W</u> indow	Help	
har	ehov.	/ 3906	enu			^
saving environment						
bar	barebox:/				~	

Reset the board, stop autobooting and type: **cat env/config**. Newly specified MAC address is saved.

```
🚨 COM1:115200baud - Tera Term VT
File Edit Setup Control Window Help
Hit any key to stop autoboot: 3
barebox:/ cat env/config
#!/bin/sh
# can be either 'net' or 'jffs2' or 'ubifs'
kernel=nand
root=ubifs
basedir=vmx53
barebox=$basedir/barebox.bin
zimage=$basedir/zImage
rootfs=$basedir/rootfs.bin
autoboot_timeout=3
# vmx53 modes
# video=mxcdi0fb:RGB24,[VGA|SVGA|XGA|WXGA|UXGA|0PTREX|DATAIMAGE],bpp=[16|24|32]
bootargs="console=ttymxc0,115200 otg mode=host video=mxcdi0fb:RGB24,XGA,bpp=16"
nand_parts="384k(barebox)ro,640k(bareboxenv),4M(kernel),-(rootfs)"
spi parts="384k(barebox)ro,128k(bareboxenv),-(kernel)"
rootpartnum_nand=3
ubiroot="rootfs"
# ip=off|static|dhcp
# use 'dhcp' to do dhcp in barebox and in kernel
ip=dhcp
# or set your networking parameters here
#eth0.ipaddr=a.b.c.d
#eth0.netmask=a.b.c.d
#eth0.gateway=a.b.c.d
#eth0.serverip=a.b.c.d
#eth0.ethaddr=00:0d:15:00:00:00
barebox:/
```

Mounting Fasteners



Additional protection of the SODIMM Module fall out of he 200pin socket, ideal for mobile applications.

Products` Life Cycle Phase

Voipac products are divided into 4 phases:

- INTRODUCTION PHASE, approximately the first 6-12 months.

The last software issues are still being resolved. Product in this stage is the most suitable for new designs.

- ACTIVE PHASE, the first 1-3 years following the product introduction.

Product software packages are stable, additional functions, OS and GUI are being released. Product in this stage is suitable for new designs.

- MATURITY PHASE, approximately the first 4-6 years after the introduction.

Products are shipped in volumes, additional functions additions declines. Product in this stage is no longer recommended for new designs.

- EOL PHASE, approximately 7-10 years after the introduction.

Used components availability decreases, although product may still be purchased under specific circumstances.

The Last Time Buy notification is send to all product users app. 6 months prior to product discontinuation.

Components stocking service for discontinued products and manufacturing of further production batches is available.

To find out the specific product life cycle phase, visit its product page and check the title color.

CE compliance of Voipac products

The CE label is a mandatory conformity mark for complex electronic devices placed on the market in the European Economic Area and each product sold within the EU needs a CE Certificate of Conformance that ensures that the product conforms to the essential requirements of the applicable EC directives.

However, if such complex electronic devices are produced for further processing by the industry, skilled development teams or system integrators, they do not need to observe the above mentioned CE requirements and consequently do not need any identification either. This applies to the Voipac SODIMM sized Computers On Module, because these are not used as stand-alone devices by the general public.

Anyway, to make sure that Voipac COMs can be used in CE marked devices, they are designed to obey the EC directives and the standard configuration SBCs manufactured by Voipac are tested for Electromagnetic Interference and operating temperature ranges plugged in corresponding Base Board and mounted in the standard Aluminium case provided to Voipac development kits.

Please visit <u>Downloads</u> for the testing reports.

TECHNICAL SUPPORT

HW & SW support: support@voipac.com

Warranty claims: warranty.claim@voipac.com

Voipac I.MX53/51/25 development kits come with prepaid 1 month support packages. All of the relevant communication between the customer and Voipac should be executed via e-mails

preferably.

Response time is up to 48 hours, except state holidays and weekends.

Voipac working hours are: 8:00 - 17:00, Monday - Friday.

Before contacting support, please read the following for the basic information about how to work with a development kit:

www.voipac.com/#Downloads http://free-electrons.com/training

Besides the free-of-charge support, we provide support for your new designs when it comes to the special drivers for the peripherals not included in the Voipac development kits, design of your own base boards, prototyping, or even new products development.

Please contact: <u>support@voipac.com</u> for more info.

Notes

Warranty:

VOIPAC TECHNOLOGIES s.r.o. Does Not Bear Responsibility for the Following:

- Failure of a product resulting from misuse, accident, modification, unsuitable operating environment, or improper maintenance by user
- Unless otherwise agreed in written, a product does not include technical support and the customer may be able to purchase technical support under separate agreement
- Any technical or other support provided under warranty by VOIPAC TECHNOLOGIES s.r.o. such as assistance, set-up and installation is provided WITHOUT WARRANTY OF ANY KIND.

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